

The tangent bundle

①

Some elements of linear algebra

Let V be a vector space, $\dim V =: k$.

Any basis $v = (v_1, \dots, v_k)$ of V yields an iso

$$\mathbb{R}^k \rightarrow V, \quad y \mapsto \sum_{j=1}^k y_j v_j = v \cdot y$$

Conversely, if $\varphi: \mathbb{R}^k \rightarrow V$ is a linear isomorphism, then the image of the standard basis of \mathbb{R}^k is a basis of V . This yields a bijective correspondence between the set of all bases of V and the set of all isomorphisms $\mathbb{R}^k \rightarrow V$.

If $w = (w_1, \dots, w_k)$ is another basis of V , we obtain the change-of-basis matrix B as follows. Writing

$$w_j = \sum_{i=1}^k b_{ij} v_i \quad (*)$$

we set $B = (b_{ij})$. Then $(*)$ is equivalent to

$$w = \underbrace{v \cdot B}_{\text{matrix multiplication}}$$

Let M be a manifold of dimension k . (2)

Pick a pt $m \in M$ and a chart (U, φ) s.t. $m \in U$.

Denote $p := \varphi(m) \in \mathbb{R}^k$. We obtain a basis of $T_m M$ as follows:

$$v_\varphi = v := ([\gamma_1], \dots, [\gamma_k]), \text{ where } \gamma_j(t) = \varphi^{-1}(p + te_j)$$

and $e = (e_1, \dots, e_k)$ is the standard basis of \mathbb{R}^k , see the remark on P. 15 of Part 4.

If $(\hat{U}, \hat{\varphi})$ is another chart s.t. $m \in \hat{U}$, we obtain another basis

$$v_{\hat{\varphi}} = \hat{v} := ([\hat{\gamma}_1], \dots, [\hat{\gamma}_k]), \text{ where } \hat{\gamma}_j(t) = \hat{\varphi}^{-1}(\hat{p} + te_j)$$

$$\text{and } \hat{p} = \hat{\varphi}(m).$$

Prop Let $\Theta := \hat{\varphi} \circ \varphi^{-1}: \mathbb{R}^k \rightarrow \mathbb{R}^k$ be the coordinate transformation map. Then the change-of-basis matrix between v and \hat{v} is $D_p \Theta$:

$$v = \hat{v} \cdot D_p \Theta.$$

Proof Without loss of generality we can assume $p = 0 = \hat{p}$.

We have

$$\hat{\varphi} \circ \gamma_j(t) = \underbrace{\hat{\varphi} \circ \varphi^{-1}}_{\Theta} \circ \underbrace{\varphi \circ \gamma_j(t)}_{te_j} = \Theta(te_j).$$

Hence,

$$d_m \hat{\varphi} [\gamma_j] = \left. \frac{d}{dt} \right|_{t=0} \Theta(t e_j) = \sum_{i=1}^k \frac{\partial \theta_i}{\partial x_j} e_i, \quad (*)$$

where the partial derivatives are evaluated at the origin (suppressed in the notations).

Notice, however,

$$\hat{\varphi} \circ \hat{\gamma}_i(t) = t e_i \Rightarrow d_m \hat{\varphi} [\hat{\gamma}_i] = e_i.$$

Hence, by (*) we obtain

$$d_m \hat{\varphi} [\gamma_j] = \sum_{i=1}^k \frac{\partial \theta_i}{\partial x_j} d_m \hat{\varphi} ([\hat{\gamma}_i])$$

$$= d_m \hat{\varphi} \left(\sum_{i=1}^k \frac{\partial \theta_i}{\partial x_j} [\hat{\gamma}_i] \right).$$

$d_m \hat{\varphi}$ is linear

Since $\hat{\varphi} : \hat{U} \rightarrow \hat{\varphi}(\hat{U}) \subset \mathbb{R}^k$ is a diffeomorphism, $d_m \hat{\varphi}$ is an isomorphism. Hence,

$$[\gamma_j] = \sum_{i=1}^k \frac{\partial \theta_i}{\partial x_j} [\hat{\gamma}_i]. \quad \square$$

Consider the set

$$TM = \bigsqcup_{m \in M} T_m M,$$

where the symbol \bigsqcup denotes the disjoint union.

(4)

This comes equipped with the map

$$\pi: TM \rightarrow M, \quad \pi(v) = m \iff v \in T_m M.$$

Example If V is a vector space, we have a canonical identification $T_m V \cong V$ for each $m \in V$, see Assignment 8, Problem 1.

Hence,

$$TV = \bigsqcup_{m \in V} \{m\} \times V = V \times V$$

and $\pi(m, v) = m$ is the projection onto the first component.

Furthermore, for any chart (U, φ) on M we have a basis $V_\varphi(m)$ of $T_m M$ for each $m \in U$. Therefore, we obtain the bijection

$$U \times \mathbb{R}^k \rightarrow \pi^{-1}(U) = \bigsqcup_{m \in U} T_m M$$

$$(m, y) \longmapsto V_\varphi(m) \cdot y = \sum_{j=1}^k y_j [\chi_j^m],$$

where $\chi_j^m(t) = \varphi^{-1}(\varphi(m) + t e_j)$. Combining this with $\varphi: U \rightarrow \varphi(U)$, which is also a bijection, we obtain a bijective map

$$\tilde{\tau} = \tau_\varphi: \varphi(U) \times \mathbb{R}^k \rightarrow \pi^{-1}(U)$$

$$(x, y) \longmapsto V_\varphi(\varphi^{-1}(x)) \cdot y = \sum_{j=1}^k y_j [\chi_j^m] \\ m = \varphi^{-1}(x).$$

Thus Let $\mathcal{U} = \{(-U_\alpha, \varphi_\alpha) \mid \alpha \in A\}$ be a (5)
 smooth atlas on M . There exists a unique
 Hausdorff topology on TM such that

$$\mathcal{V} = \{(\pi^{-1}(U_\alpha), \tau_\alpha^{-1}) \mid \alpha \in A\}$$

is a C^0 -atlas on TM , where $\tau_\alpha = \tau_{\varphi_\alpha}$. In fact,
 \mathcal{V} is a smooth atlas so that TM is a
 smooth manifold of dimension $2k$. Moreover, π
 is a smooth map with surjective differential
 at each point.

Proof The proof consists of the following steps.

Step 1 For the coordinate transformation

$$\Theta_{\alpha\beta} = \tau_\alpha^{-1} \circ \tau_\beta \quad \text{on } TM \quad \text{we have}$$

$$\Theta_{\alpha\beta}(x, y) = (\Theta_{\alpha\beta}(x), D_x \Theta_{\alpha\beta} \cdot y).$$

In particular, $\Theta_{\alpha\beta}$ is smooth.

$$\text{Denote } \tau_\beta(x, y) = v \quad \Rightarrow$$

$$\varphi_\beta(\pi(v)) = x \quad \text{and} \quad v = V_\beta \stackrel{=:m}{=} (\varphi_\beta^{-1}(x)) \cdot y.$$

By the proposition on P. 2 we have

$$V_\beta(m) = V_\alpha(m) D_x \Theta_{\alpha\beta}$$

$$\text{Denote } \tau_\alpha^{-1}(v) = (s, t) \in \mathbb{R}^k \times \mathbb{R}^k$$

Then

(6)

$$s = \varphi_\alpha^{-1}(\pi(v)) = \varphi_\alpha^{-1}(\varphi_\beta^{-1}(x)) = \Theta_{\alpha\beta}(x)$$

$$t = D\Theta_{\alpha\beta} \cdot y \quad \text{since} \quad v = \varphi_\beta^{-1}(x) \cdot y = \varphi_\alpha^{-1} \cdot D\Theta_{\alpha\beta} \cdot y$$

Step 2 We construct the topology on TM .

Declare a set $V \subset TM$ to be open if and only if $\tau_\alpha^{-1}(V)$ is open in \mathbb{R}^{2k} for any $\alpha \in A$.

We have

(i) \emptyset is open and $\tau_\alpha^{-1}(TM) = \varphi_\alpha^{-1}(U_\alpha) \times \mathbb{R}^k$ is open.

(ii) V_1, V_2 are open $\Rightarrow \tau_\alpha^{-1}(V_1 \cap V_2) = \tau_\alpha^{-1}(V_1) \cap \tau_\alpha^{-1}(V_2)$
is open $\Rightarrow V_1 \cap V_2$ is open

(iii) Each $V_\beta, \beta \in B$, is open \Rightarrow

$$\Rightarrow \tau_\alpha^{-1}\left(\bigcup_{\beta \in B} V_\beta\right) = \bigcup_{\beta \in B} \tau_\alpha^{-1}(V_\beta) \text{ is open}$$

$$\Rightarrow \bigcup_{\beta \in B} V_\beta \text{ is open.}$$

Hence, we obtain a topology on TM s.t. π is continuous. Moreover, each $(\pi^{-1}(U_\alpha), \tau_\alpha^{-1})$ is a chart on TM .

This topology is Hausdorff. Indeed, pick $v_1, v_2 \in TM, v_1 \neq v_2$.

(a) If $\pi(v_1) \neq \pi(v_2)$, choose open subs. $U_1, U_2 \subset M$ s.t. U_1 and U_2 separate $\pi(v_1)$ and $\pi(v_2)$. Then $\pi^{-1}(U_1)$ and $\pi^{-1}(U_2)$ separate $\pi(v_1)$ and $\pi(v_2)$.

(6) If $\pi(v_1) = \pi(v_2) =: m$. Pick any chart (7)
 (U, φ) s.t. $m \in U$. Then $\tau(U \times V_1)$ and $\tau(U \times V_2)$ separate v_1 and v_2 if $V_1, V_2 \subset \mathbb{R}^k$ separate $\pi_2(\tau^{-1}(v_1))$ and $\pi_2(\tau^{-1}(v_2))$.

Step 3 We finish the proof of this theorem.

Pick a chart $(U_\alpha, \varphi_\alpha)$ on M , hence also a chart $(\pi^{-1}(U_\alpha), \tau_\alpha^{-1})$ on TM . The coordinate representation of π with respect to these charts is

$$\varphi_\alpha \circ \pi \circ \tau_\alpha^{-1}(x, y) = \varphi_\alpha(\varphi_\alpha^{-1}(x)) = x$$

$$\Rightarrow \varphi_\alpha \circ \pi \circ \tau_\alpha^{-1} = \pi_1$$

$\Rightarrow \pi$ is smooth and $d_v \pi$ is surjective. \square

Example 1) For $M = S^k$ the tangent bundle can be identified with

$$\{(x, y) \in S^k \times \mathbb{R}^{k+1} \mid \langle x, y \rangle = 0\} \subset \mathbb{R}^{2k+2}.$$

If $k=1$, this yields TS^1 as a submanifold in \mathbb{R}^4 . In fact, we can realize TS^1 as a surface in \mathbb{R}^3 as follows. Consider the map

$$f: S^1 \times \mathbb{R} \rightarrow \mathbb{R}^3, \quad f(x_0, x_1; t) = (x_0, x_1, tx_1, -tx_0)$$

The reader should check that f is a diffeomorphism between the cylinder $S^1 \times \mathbb{R}$ and $TS^1 \subset \mathbb{R}^4$.

2) If $S \subset \mathbb{R}^3$ is a surface, then the tangent bundle of S can be identified with $\{(x, y) \in S \times \mathbb{R}^3 \mid y \in T_x S\} \subset \mathbb{R}^6$.

Vector fields and their integral curves

Defn A smooth map $v: M \rightarrow TM$ such that $\pi \circ v = id_M \iff v(m) \in T_m M \forall m \in M$ is called a (smooth) vector field on M .

Example 1) Let $S \subset \mathbb{R}^3$ be a surface and v be a smooth vector field on S . This means that $v(p) \in T_p S$, i.e., we can view v as a map $S \rightarrow \mathbb{R}^3$ s.t. $v(p) \in T_p S \forall p \in S$. It is an exercise to check that v is smooth if and only if v is smooth as a map $S \rightarrow \mathbb{R}^3$.

2) Just like in the case of surfaces, we can view a vector field on S^k as a map $v: S^k \rightarrow \mathbb{R}^{k+1}$ s.t. $v(x) \in T_x S^k \iff \langle v(x), x \rangle = 0$. For example, if $k=1$

$$v(x) = (-x_1, x_0)$$
 is a vector field on S^1 .